



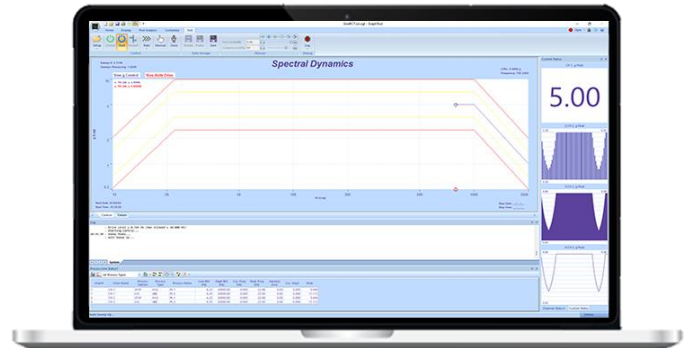
Sine testing can be done two ways:

1. Overall test level control, where we do not care about what frequency causes the response energy.
2. Fundamental Control, which requires Tracking Filters. See Figure 2 below

Nearly all tests presume Tracking Filters are being employed. LYNX™ provides True analog quality tracking filters created in DSP with the same Sine-Co-Sine Heterodyne method SD patented in 1961, If you must test to MilStd expectations, you must use tracking filters. FFT based processes DO NOT yield the same accuracy that Digital Tracking Filters offer.

Signal Generation hardware matters. LYNX™ generates harmonic free analog quality Sine signals that permit remarkable resonance control and accuracy.

NOT generating Harmonic content, means the power amplifier WON'T receive high frequency energy which it CANNOT reproduce, thereby removing another worry from the Test Professional's mind.



FEATURES

- Analog quality sine signal generation
- Multi-channel digital tracking filters with variable fixed and proportional bandwidths
- Digital re-sampling provides true proportional bandwidth tracking filters
- Sweep range from 0.1 to 10,000 Hz
- Optional resonance search and phase-tracked dwell
- Frequency Response Function (FRF) measurements for all active channels
- Independent limit profiles for each active measurement channel



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|----------------------------------|--|--|---|
| Control Methods | | | |
| Control loop | True analog-quality sine sweep with a double precision integrated phase algorithm for low distortion | Sweep duration | User-defined, maximum 999:59:59 (hhh:mm:ss) |
| Control Performance | | Number of sweeps | 0.01 to 100,000 |
| Dynamic range | Greater than 80 dB with 0.05 dB level step control over the full range | Sweep rate-linear | 0.00003 to 300 Hz/sec (0.0018 to 18,000Hz/min) |
| Output signal | Analog-quality digital sine generation, using a double precision integrated phase algorithm for low distortion | Sweep rate-logarithmic | 0.1 to 800 Oct/min |
| Level accuracy | Control to within ± 1 dB at a sweep rate of 1 oct/min through a 600 Hz resonance of a linear system with a Q of 70 with an internal 20% proportional tracking filter | Initial sweep direction | Up, down |
| Loop time | Less than 5 msec for single channel control | Safety Features | |
| Compression rate | Up to 3,500 dB/sec with unconditionally stable feedback control loop | Shaker limits | Pretest verification that spectrum dynamic limits are within shaker operational limits (acceleration, velocity, displacement and voltage) |
| Harmonic distortion | < -75 dB at full output | Loop check max. drive | User-selectable, 0 to 5,000 mV RMS |
| Reference Profile | | Control signal loss | Continuous automatic detection |
| Definition | Up to 500 frequency segments | Manual abort | Graphical and keyboard abort buttons |
| Segment types | Constant displacement, velocity, acceleration, and straight line acceleration (linear or logarithmic) | Maximum drive signal | 0.0001 to 12 V peak |
| Crossover frequencies | Automatically calculated to avoid segment boundary discontinuities | Startup/shutdown rates | Independently selectable, 1 to 99 dB/sec |
| Alarm and abort limits | Independent positive and negative alarm and abort margins | Test Automation | |
| Sweep range | User-defined sweep range from 1 to 5000 Hz; and 0.01 to 10000 Hz (Premier) optional | Test scheduling | User-defined sequence of up to 500 independent tests run automatically |
| Sweep resolution | User-defined resolution of 450 to 800 points per sweep; 450 to 2400 points per sweep (Premier) optional | Sweep rate table | Up to 50 sweep rate vs. frequency segments |
| Spectrum dynamic limits | Acceleration range, maximum or minimum acceleration, maximum velocity and maximum displacement | Compression table | Up to 50 compression speed vs. frequency segments |
| Limit Profiles (optional) | | Schedule cycles | 1 to 100 |
| Definition | Up to 500 frequency segments | Print Automation | Ability to create reports Automatically with Customized displays |
| Segment types | Constant displacement, velocity, acceleration, and straight-line acceleration (linear or logarithmic) | Base Engineering Units | Label(EU), Conversion(EU/Transducer Units) |
| Crossover frequencies | Automatically calculated to avoid segment boundary discontinuities | Engineering Units | Integrated (Label and Scale Factor), Double |
| Number | Up to the number of active channels minus one (Premier) | Calculations | Integrated(Label and Scale Factor), Differentiated (Label and Scale Factor), Double Differentiated (Label and Scale Factor) |
| Control Parameters | | Channel Setup | |
| Mode of operation | Manual, automatic | Channel type | Control, measurement, reference, limit, abort, inactive |
| Test duration | Maximum 99,999 sweeps or 9999:59:59 (hhh:mm:ss); unlimited test | Sensitivity | 0.001 to 999,999 mV/g or mV/(m/s ²) mm; EU for Measurement Channels |
| Measurement processing | RMS, or tracking filter processing for all channels in parallel; processing type individually selectable for each channel | Channel loop check | Enabled, disabled |
| Tracking filter types | Proportional to drive frequency, 1 to 200% and fixed bandwidth, 1 Hz to 1,000Hz | Channel label | Up to 20 characters for each channel |
| Transducer types | Control based on acceleration, velocity, displacement (transducer with programmable transition frequency band) | Transducer serial number | Up to 10 characters for each channel |
| Number of control channels | 1 to all available channels, max 16 | Transducer Database | Table Driven Archival Database |
| Multi-channel control strategy | RMS, arithmetic average, min, max | On-Line Test Analysis | |
| Abort channels | Abort test when user-defined level exceeded | Display functions | Control, drive, measurement channel 1 to 32, frequency response function (magnitude/phase or real/imaginary) |
| Compression | 5% to 100% | Cursors | X and Y value readout, peak search, trace tagging, multi-window looked positioning |
| Units | m/s ² - m/s - mm; g - in/sec - in; g - m/s - mm | Scaling of display | Log/linear, auto-scaled/fixd |
| Box Tolerance Enable | Alarm & Abort width set 0 to 100% | Real-time/stored data | Simultaneous display and overlay of real-time data and any stored data |
| Startup/Shutdown Rate | 1 to 99 dB/sec | Passive Sine Analysis | Same capability as test operations w/o output generation |
| Sweep Parameters | | Resonance Search & Dwell (optional) | |
| Sweep mode | Linear, logarithmic | Dwell modes | Fixed frequency, phase tracked(auto/manual), Continuous (w/reset option) |
| | | Search parameters | Max no. of resonances, hysteresis, minimum Q value |
| | | Q Search | Peak Ratio or -3dB points |
| | | Smoothing | Low, Medium, High |
| | | Search Channel | Any active channel |
| | | Phase Reference Channel | Any active channel |
| | | Resonance calculation | Resonance frequency, Q, phase, level |
| | | Dwell table parameters | Duration, start frequency, dwell frequency, end frequency, dwell level and phase, alarm limit, abort limit |
| | | Dwell level type | Acceleration, velocity, displacement |
| | | Data Storage | |
| | | Setup options | Sweep Increment, first sweep, last sweep |
| | | Playback | Scan through the entire test data file, with adjustable |

Lynx™ Sine - Technical Specifications

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|------------------------|---|
| | delay and tagging |
| Documentation | |
| Test summary | Fully documented post-test summary, easily printed or incorporated into any document using standard word processing software |
| Run message log | Text file records all system status messages displayed during test run |
| Safety Features | |
| Shaker limits | Pretest verification that spectrum dynamic limits are within shaker operational limits (acceleration, velocity, displacement and voltage) |
| Loop check max. drive | User-selectable, 0 to 5,000 mV RMS |
| Control signal loss | Continuous automatic detection |
| Manual abort | Graphical and keyboard abort buttons |
| Maximum drive signal | 0.0001 to 12 V peak |
| Startup/shutdown rates | Independently selectable, 1 to 99 dB/sec |